



# *Semi-Lagrangian characteristic reconstruction and projection for transport under incompressible velocity fields*

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first.  
further.  
forward.

# Scalar Advection

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Forward Euler, Upwind Scheme

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0 \quad \longrightarrow \quad \phi^{n+1} = \phi^n + \frac{\mathbf{u} \Delta t}{\Delta x} (\phi_i^n - \phi_{i-1}^n)$$

Lagrangian Form



$$\frac{D\phi}{Dt} = 0$$

Constant along characteristics

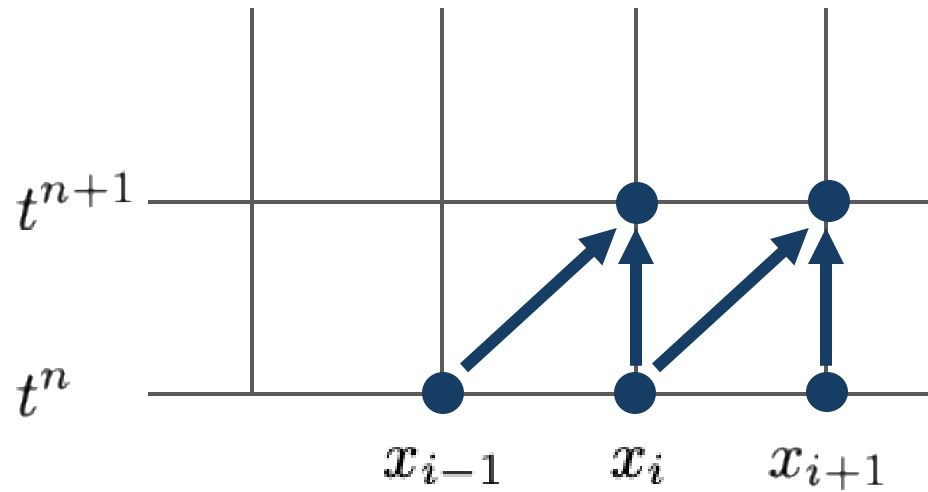
$$\frac{Dx}{Dt} = \mathbf{u}$$

Characteristic velocity

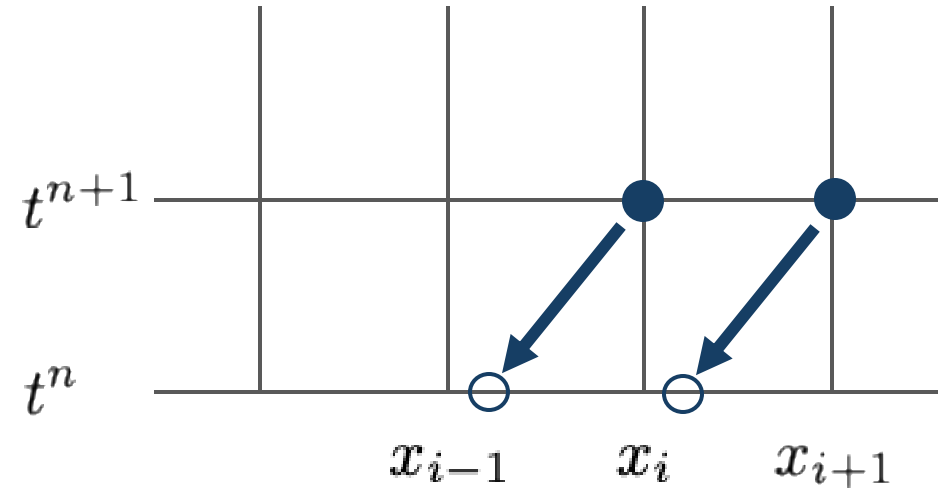
# Semi-Lagrangian Method

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Forward Euler, Upwind



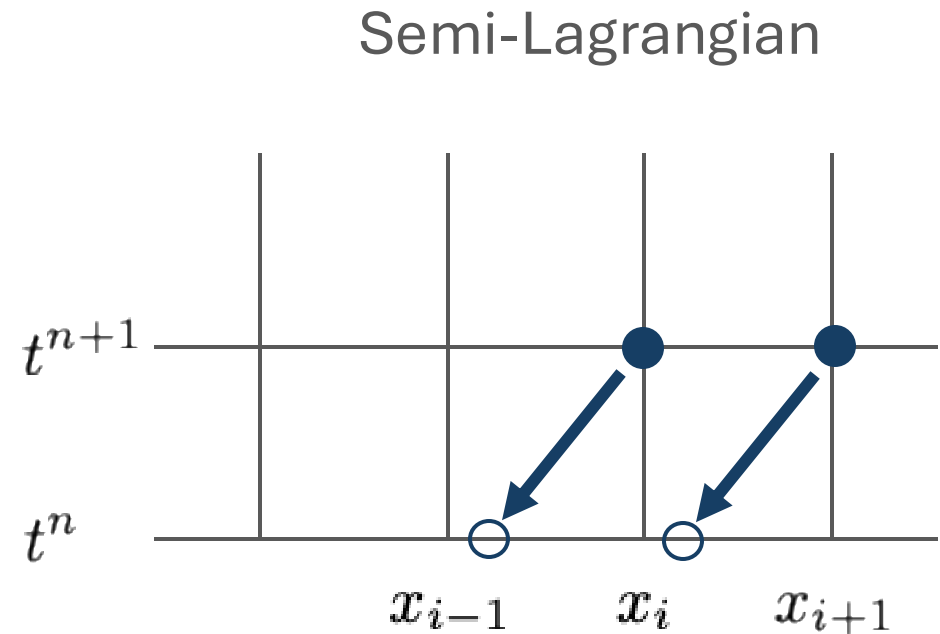
Semi-Lagrangian



# Semi-Lagrangian Method

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- Pros:
  - Unconditionally stable for linear advection (no CFL restriction).
  - Very good at resolving fronts, sub-grid features.
- Cons:
  - Not strictly conservative.
  - Grid search and interpolation.





# Reference Map

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0$$

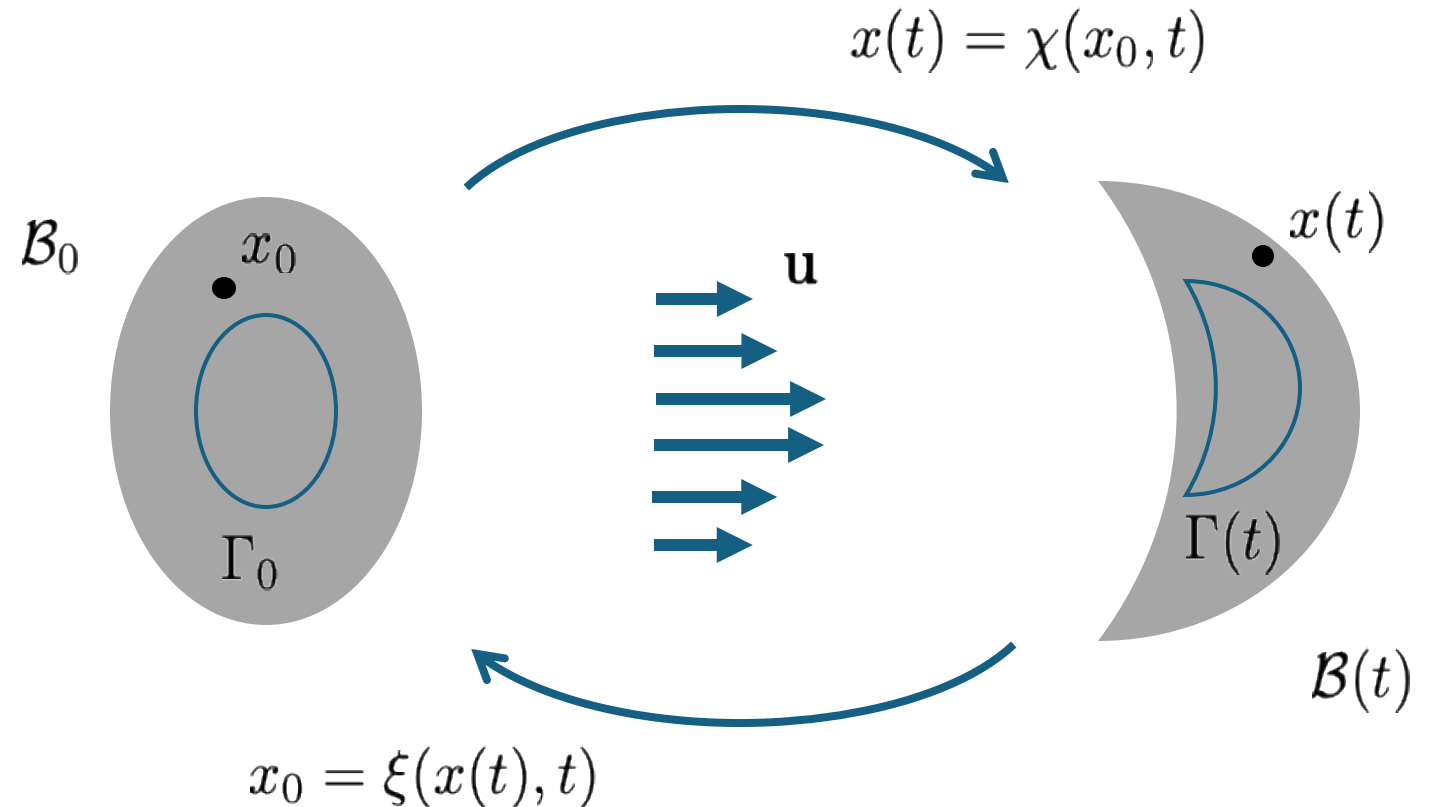


Advection

$$\frac{\partial \xi}{\partial t} + \mathbf{u} \cdot \nabla \xi = 0$$

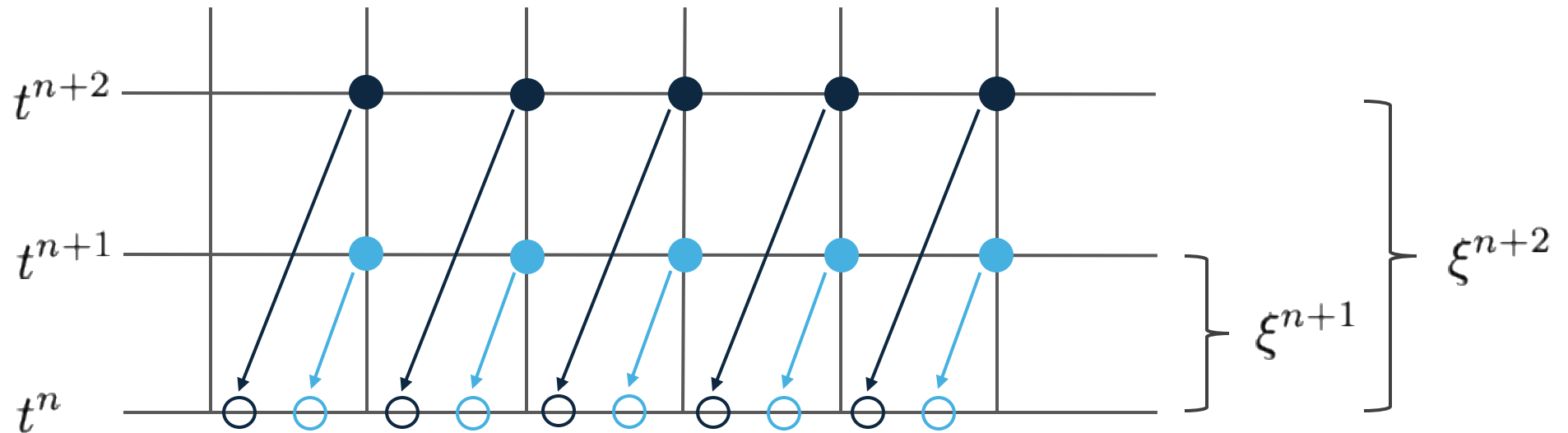
Reconstruction

$$\phi(x, t) = \phi(\xi(x(t), 0))$$



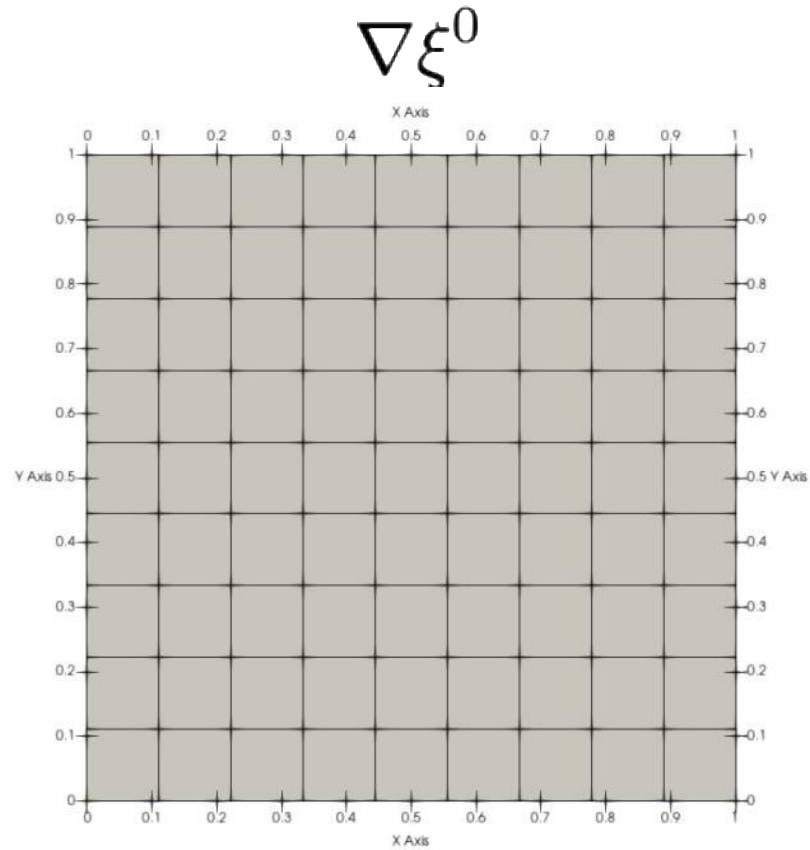
# Semi-Lagrangian as the Reference Map

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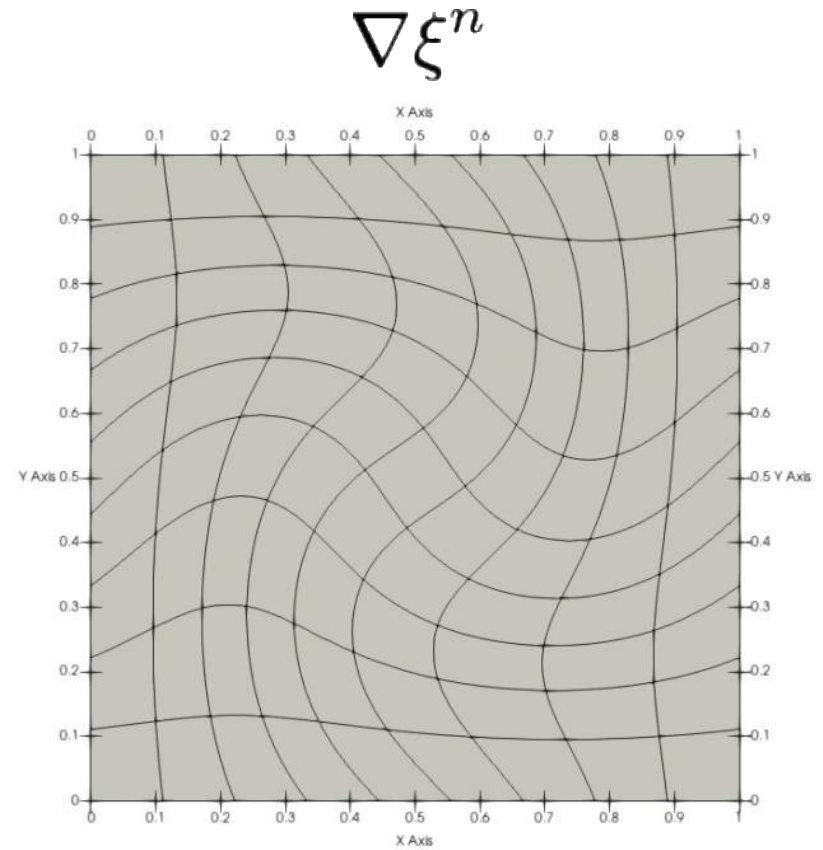


# Gradient of the Reference Map

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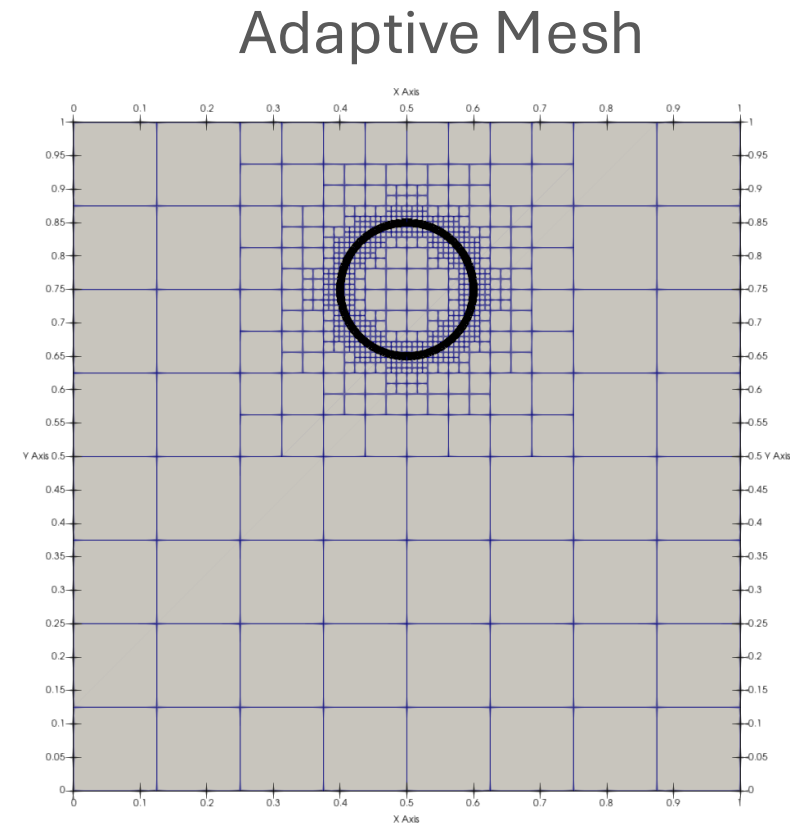
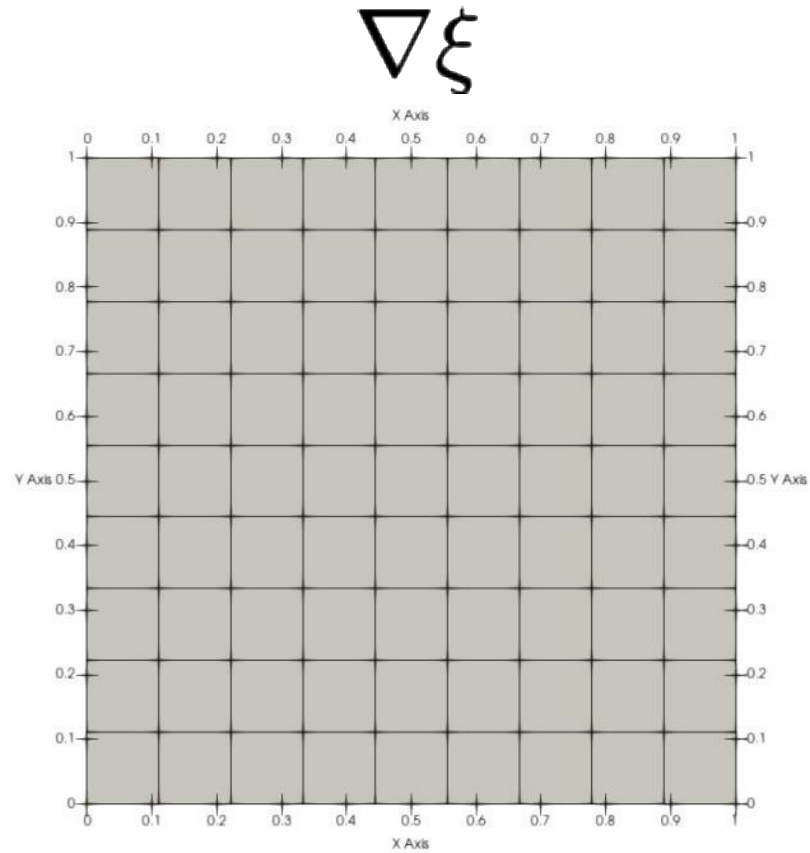


$$\det(\nabla \xi) = 1$$



$$\det(\nabla \xi) \neq 1$$

# Contours of $\nabla\xi$ vs. Adaptive Mesh





# Volume Preserving Projection

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## 1. Advect the Reference Map

$$\frac{\partial \xi}{\partial t} + \mathbf{u} \cdot \nabla \xi = 0$$

## 2. Project onto the Volume Preserving Space

Solve for the adjoint  $\lambda$ :

$$-\Delta \lambda = 1 - \det(\nabla \xi) \quad \forall x \in \Omega$$

$$\lambda = 0 \quad \forall x \in \partial\Omega$$

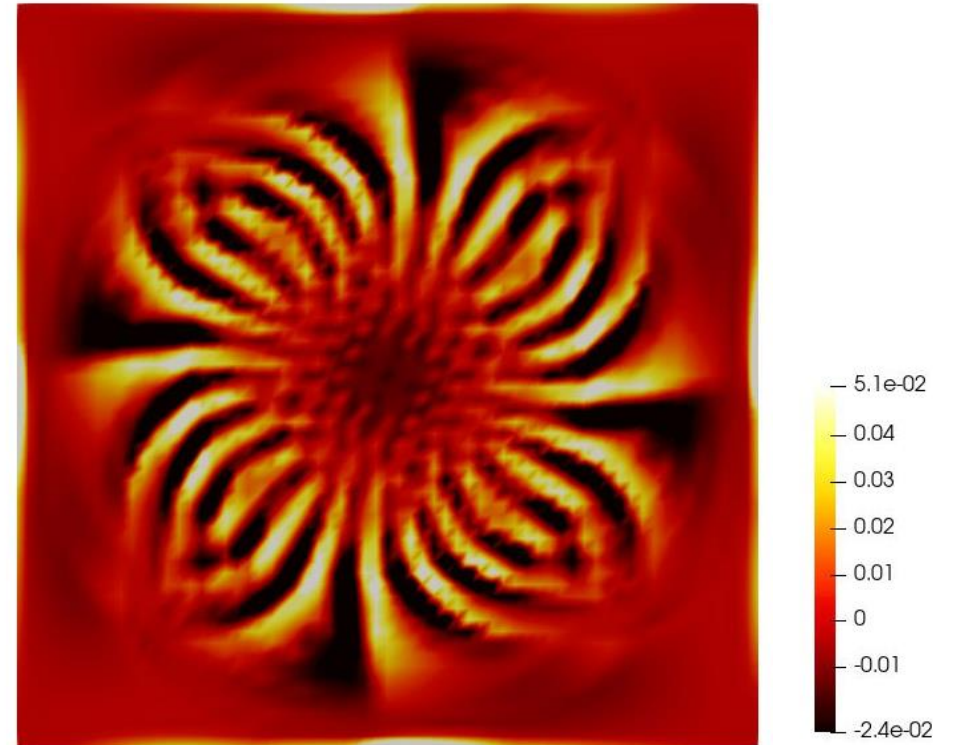
Compute the correction

$$\gamma^{-1}(x) = x - \nabla \lambda$$

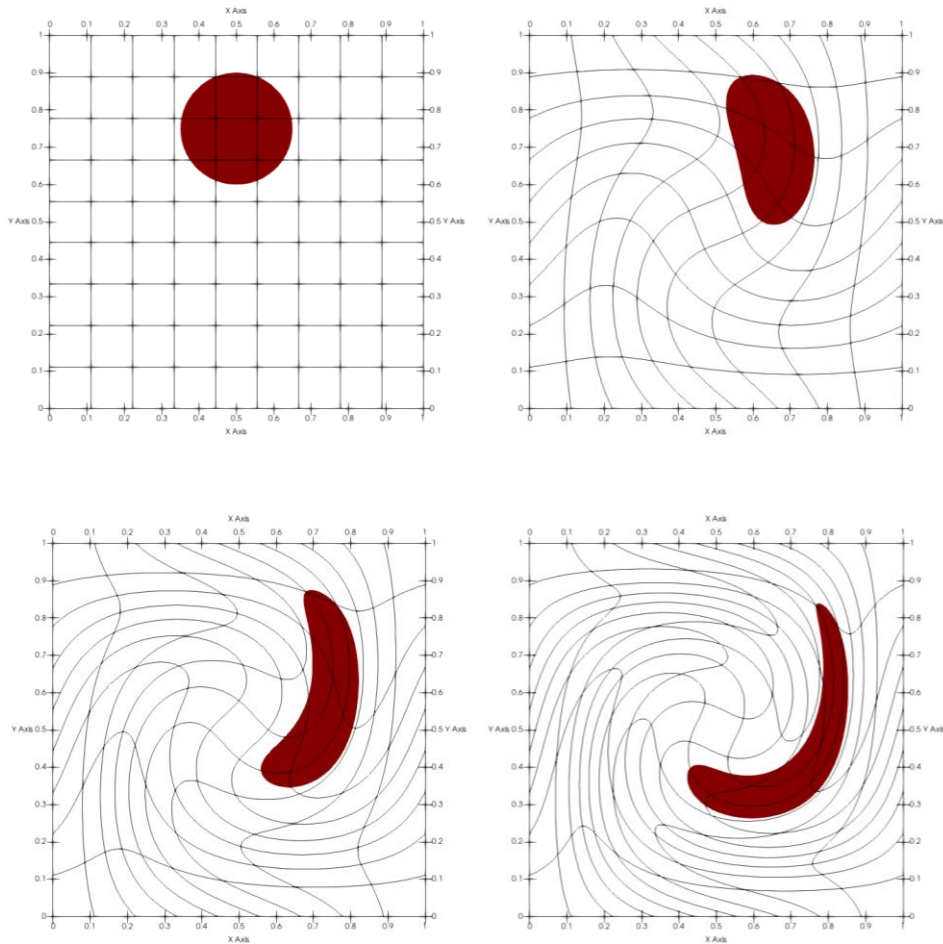
## 3. Reconstruction

$$\phi^{n+1}(x) = \phi_0(\xi^{n+1}(\gamma^{-1}(x)))$$

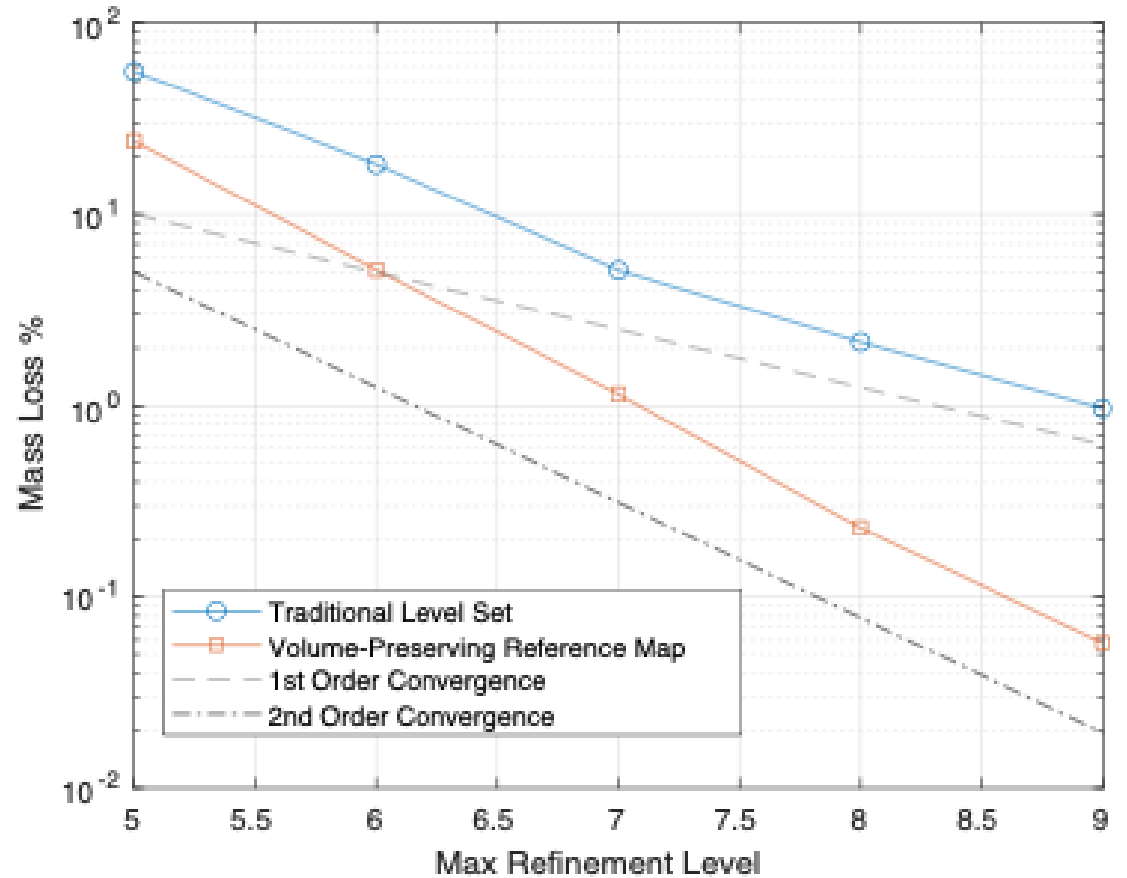
$1 - \det(\nabla \xi)$  for the Single Vortex example



# Single Vortex

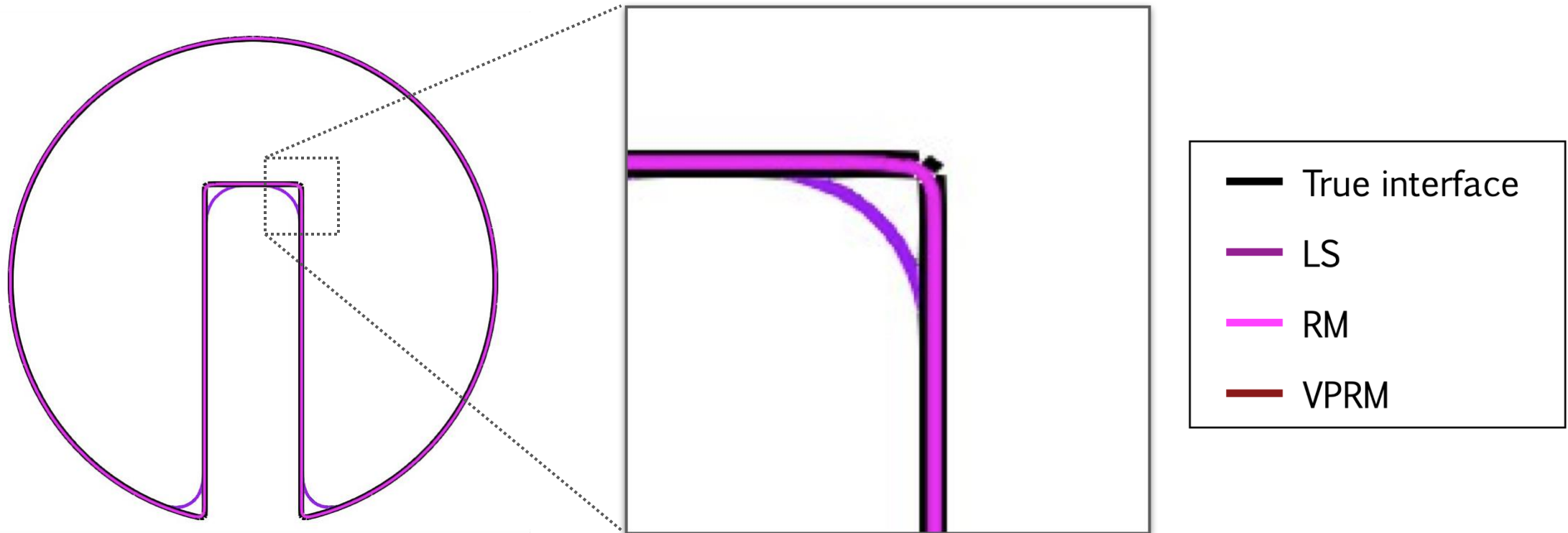


## Mass Loss for Single Vortex



# Slotted Circle

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# Summary

1. Reference map formulation provides a metric for measuring the deformation of the space.
2. Volume preserving projection minimizes mass loss.
3. Together, this preserves interface location and prevents mass loss.

Joint work with:

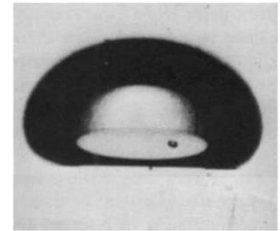
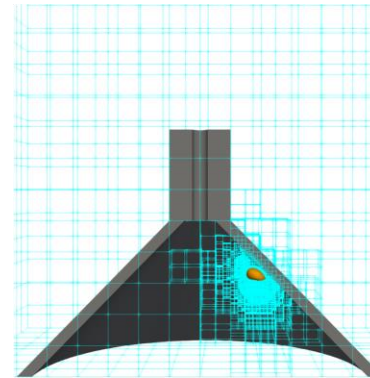
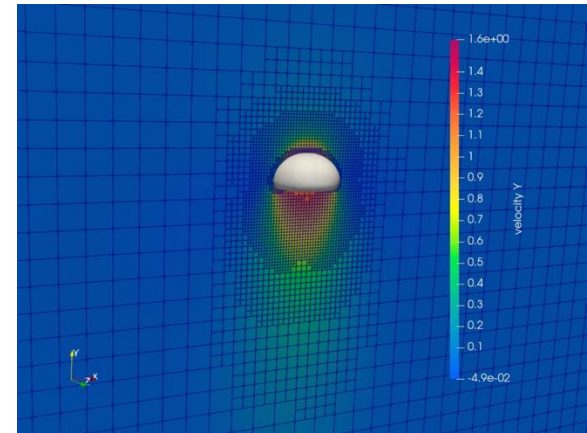
Adam Binswanger, Maxime Theillard (advisor), Scott West

## Papers

A. Binswanger, M. Blomquist, S. R. West, and M. Theillard, “A stable nodal projection method for two-phase flows”, In Preparation.

M. Blomquist, S. R. West, A. L. Binswanger, and M. Theillard, “Stable nodal projection method on octree grids”, *Journal of Computational Physics* 499, 112695 (2024).

M. Theillard, A volume-preserving reference map method for the level set representation, *Journal of Computational Physics* 422, 110478 (2021).



Simulation

Bhaga, Weber '81

