



Characteristic Bending

A Robust Advection Scheme for Incompressible Flows

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Characteristic Bending

Big Picture

Question

If we know that our velocity field is (or should be) incompressible, can we use this information to design a robust advection scheme?

A diagram consisting of three dark blue ovals with white text. The ovals are arranged in a triangular pattern: one on the left, one on the right, and one centered below them. Each oval contains a specific type of error.

Spatial
Interpolation Error

Velocity Error
(Inexact Projection)

Time Integration
Error

Characteristic Bending

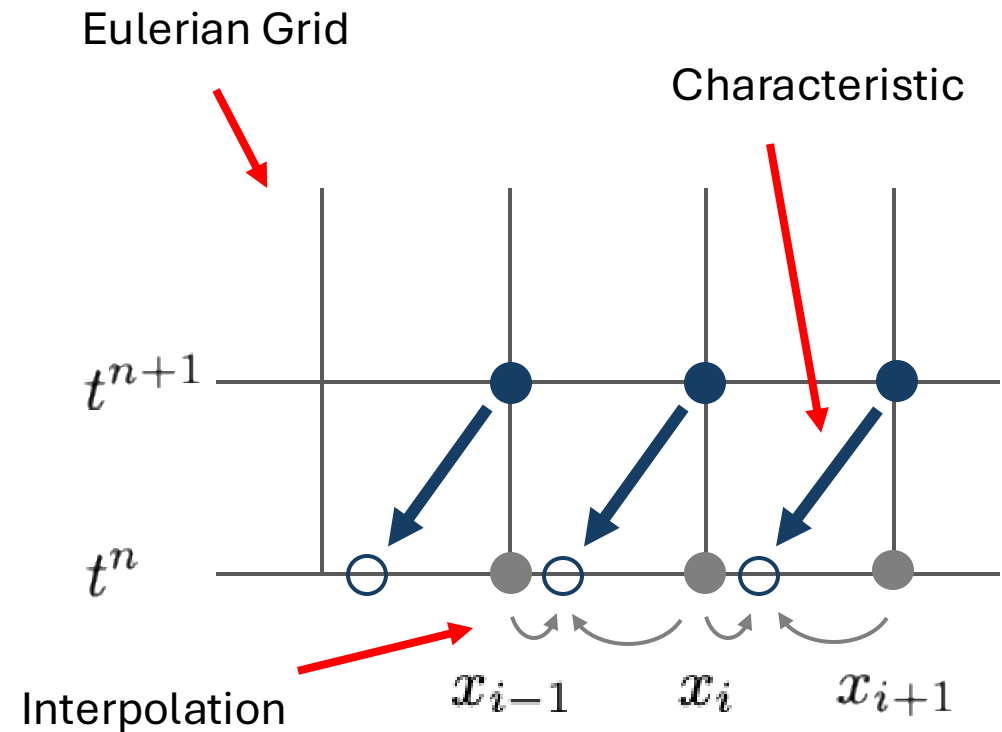
Semi-Lagrangian Method

Eulerian Frame

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0$$

Lagrangian Frame

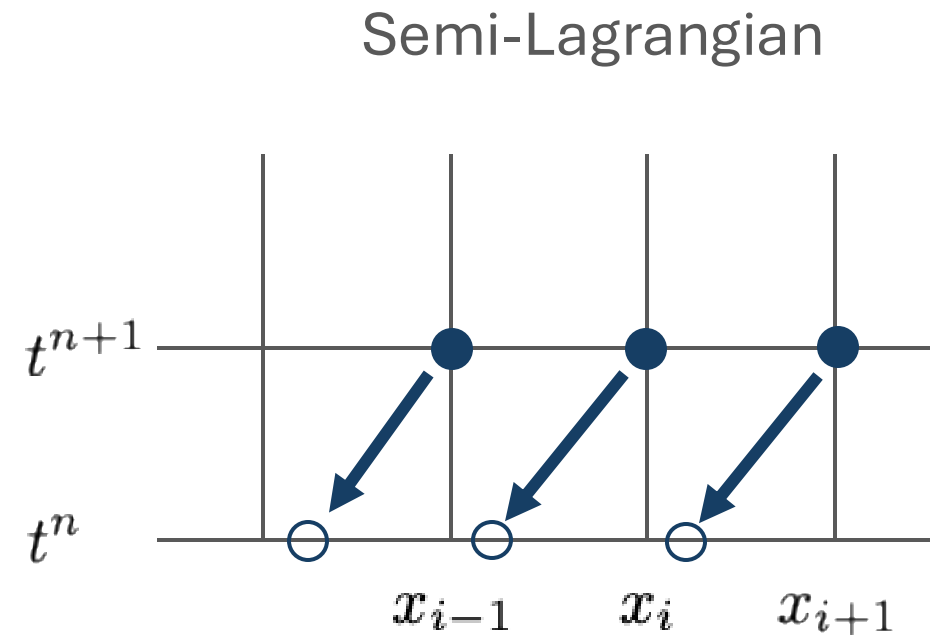
$$\frac{Dx}{Dt} = \mathbf{u} \qquad \frac{D\phi}{Dt} = 0$$



Characteristic Bending

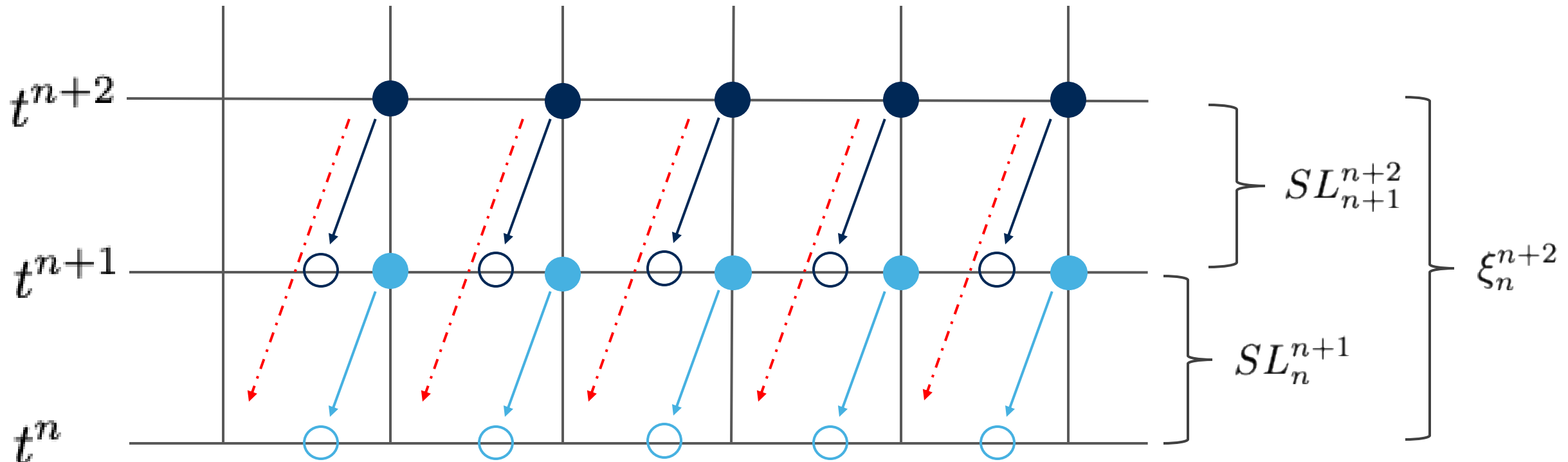
Semi-Lagrangian Method

- Pros:
 - Unconditionally stable for linear advection (no CFL restriction).
 - Very good at resolving fronts, sub-grid features.
- Cons:
 - Single step method.
 - No inherent mechanism for preserving incompressibility, conservation, etc.



Characteristic Bending

Characteristic Reconstruction



Characteristic Bending

Reference Map Advection

$$\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0$$

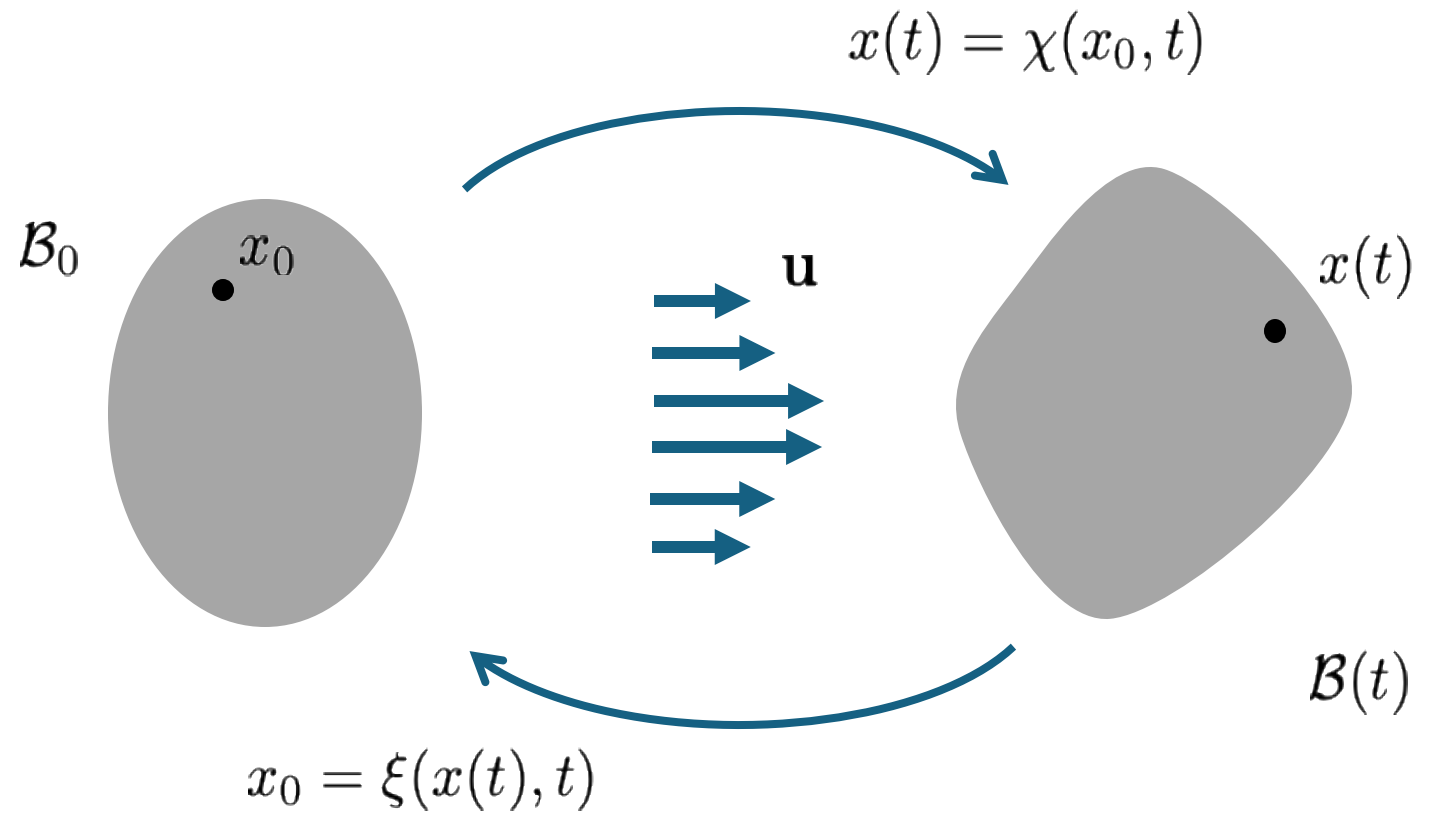


Advection

$$\frac{\partial \xi}{\partial t} + \mathbf{u} \cdot \nabla \xi = 0$$

Reconstruction

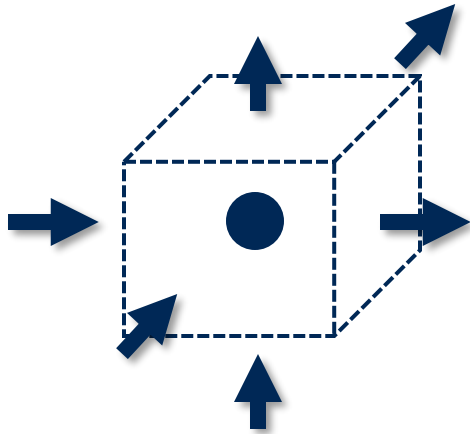
$$\phi(x, t) = \phi(\xi(x(t), 0))$$



Characteristic Bending

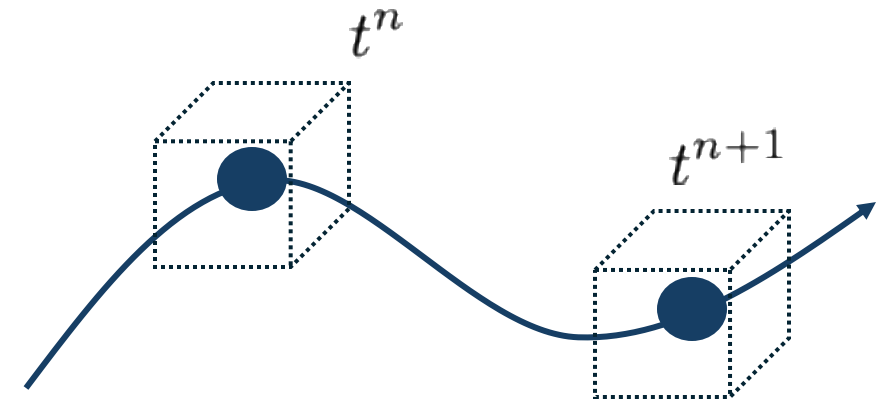
Incompressibility vs. Volume Preservation

Eulerian Frame



$$\nabla \cdot \mathbf{u} = 0$$

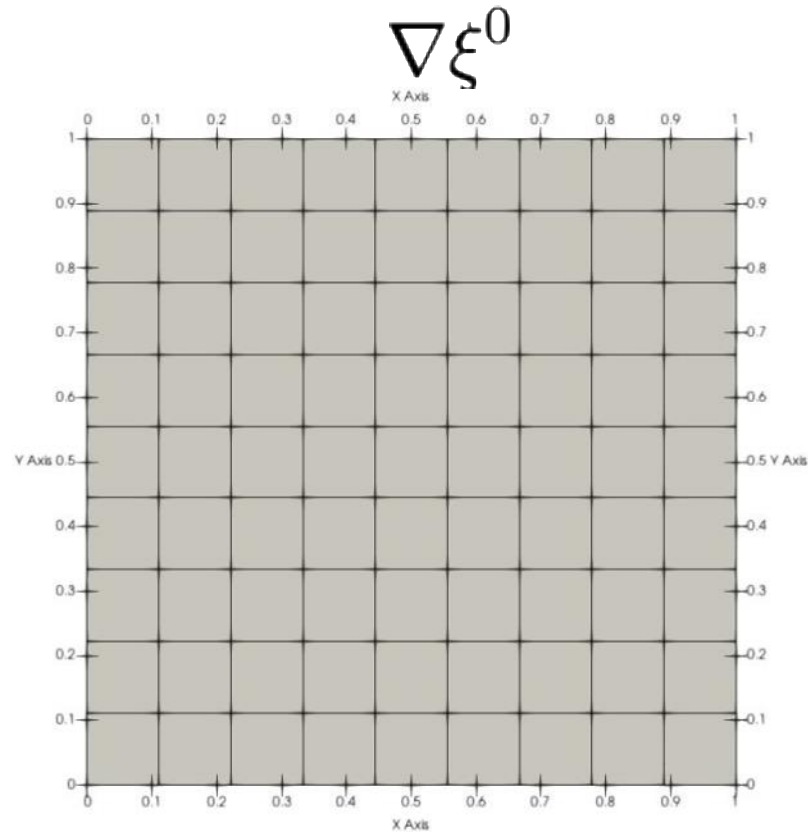
Lagrangian Frame



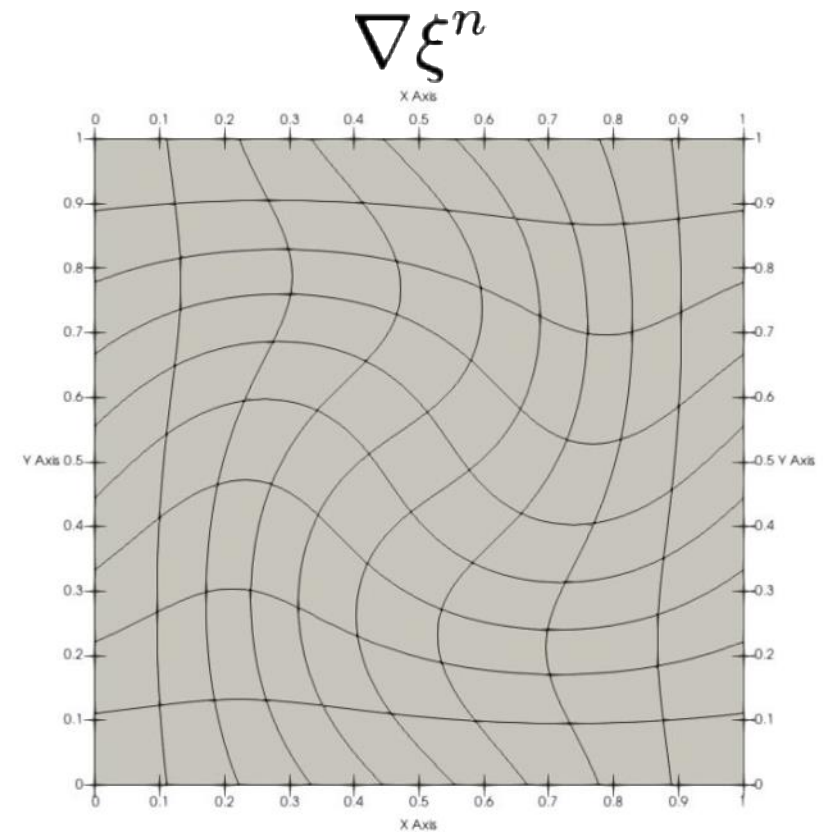
$$V^n = V^{n+1}$$

Characteristic Bending

Deformation of the Space



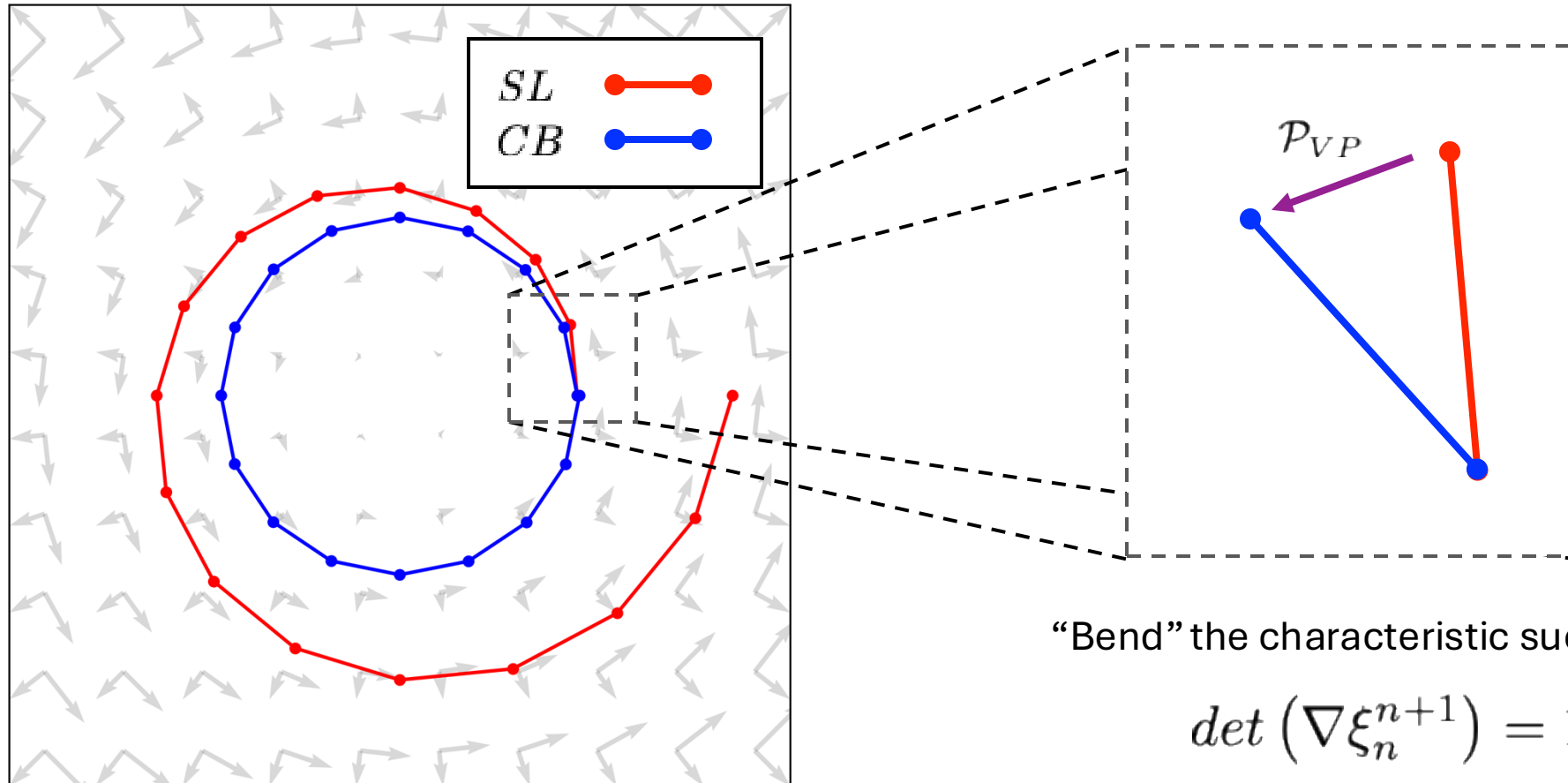
$$\det(\nabla \xi) = 1$$



$$\det(\nabla \xi) \neq 1$$

Characteristic Bending

Bending the Characteristics



“Bend” the characteristic such that:

$$\det(\nabla \xi_n^{n+1}) = 1$$

Characteristic Bending

Formal Algorithm

1. Initialize and advect a Reference Map

$$\frac{\partial \xi}{\partial t} + \mathbf{u} \cdot \nabla \xi = 0$$

2. Project onto the Volume Preserving Space

Solve for the adjoint λ :

$$-\Delta \lambda = 1 - \det(\nabla \xi^*) \quad \forall \mathbf{x} \in \Omega$$

$$\lambda = 0 \quad \forall \mathbf{x} \in \partial\Omega$$

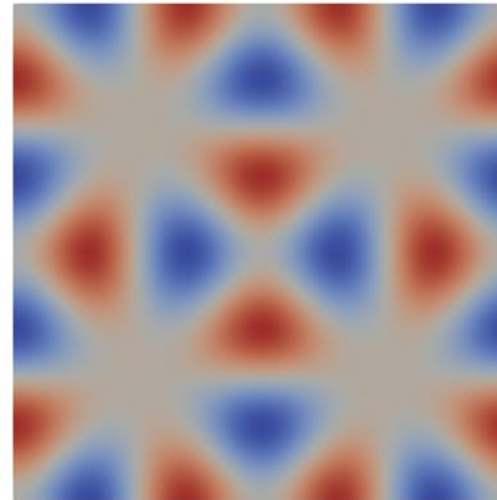
Compute the correction

$$\gamma^{-1}(\mathbf{x}) = \mathbf{x} - \nabla \lambda$$

3. Reconstruction

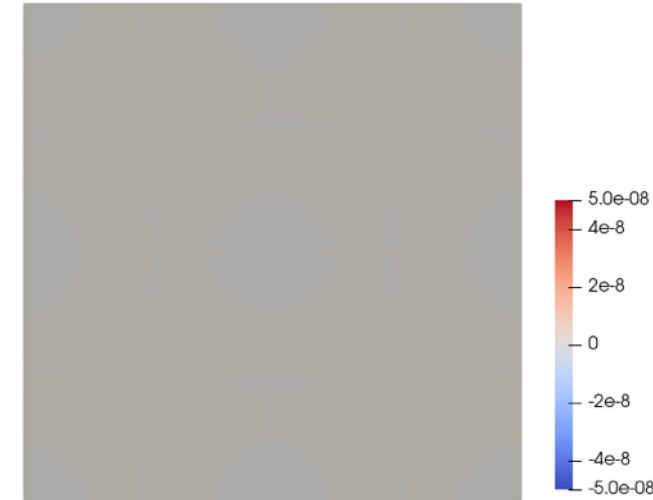
$$\phi^{n+1}(\mathbf{x}) = \phi^n(\xi^*(\gamma^{-1}(\mathbf{x})))$$

$$1 - \det(\nabla \xi^*(\mathbf{x}))$$



Intermediate Map

$$1 - \det(\nabla \xi^*(\gamma^{-1}(\mathbf{x})))$$

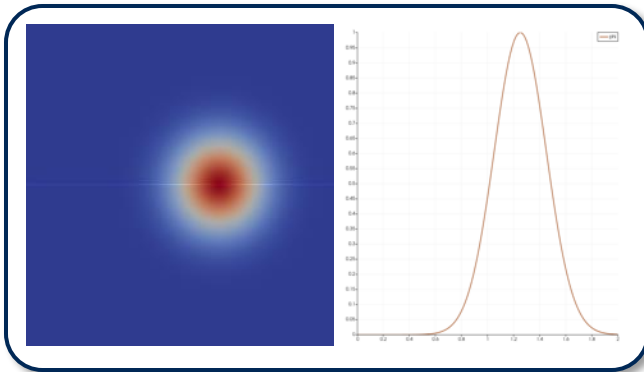


Corrected Map

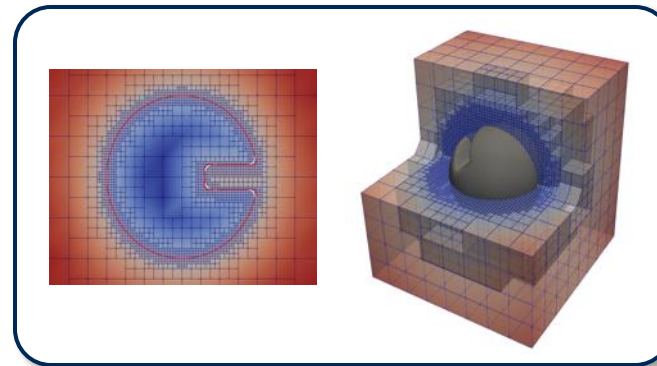
Characteristic Bending

Examples

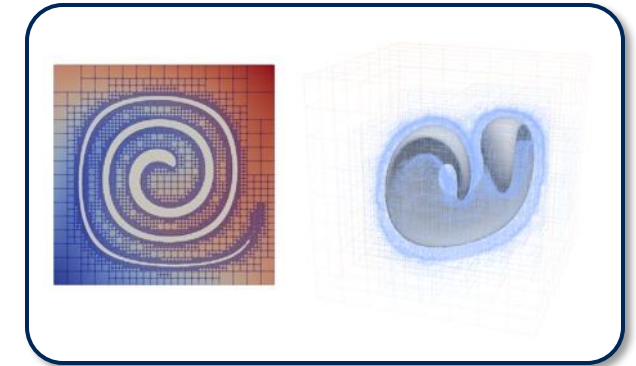
Gaussian Advection



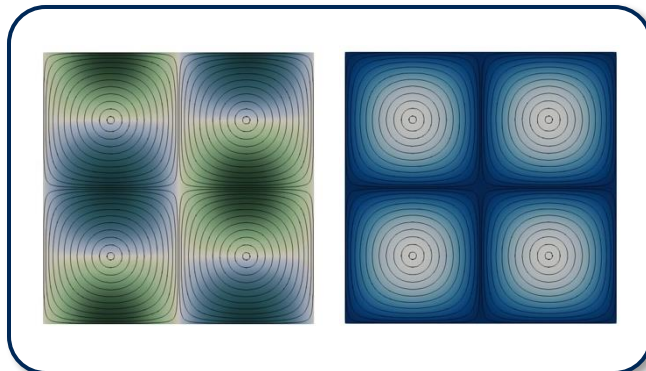
Solid Body Rotation



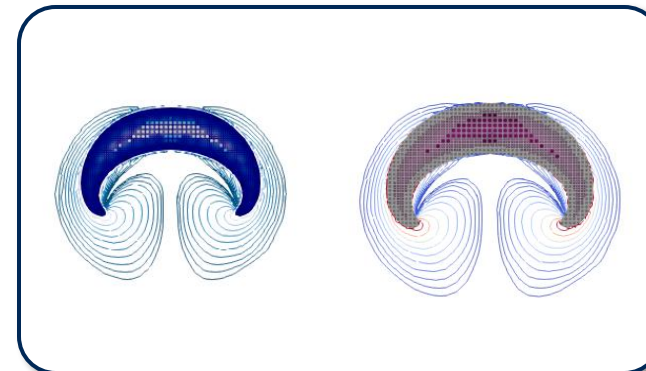
Deforming Flow



Incompressible Euler



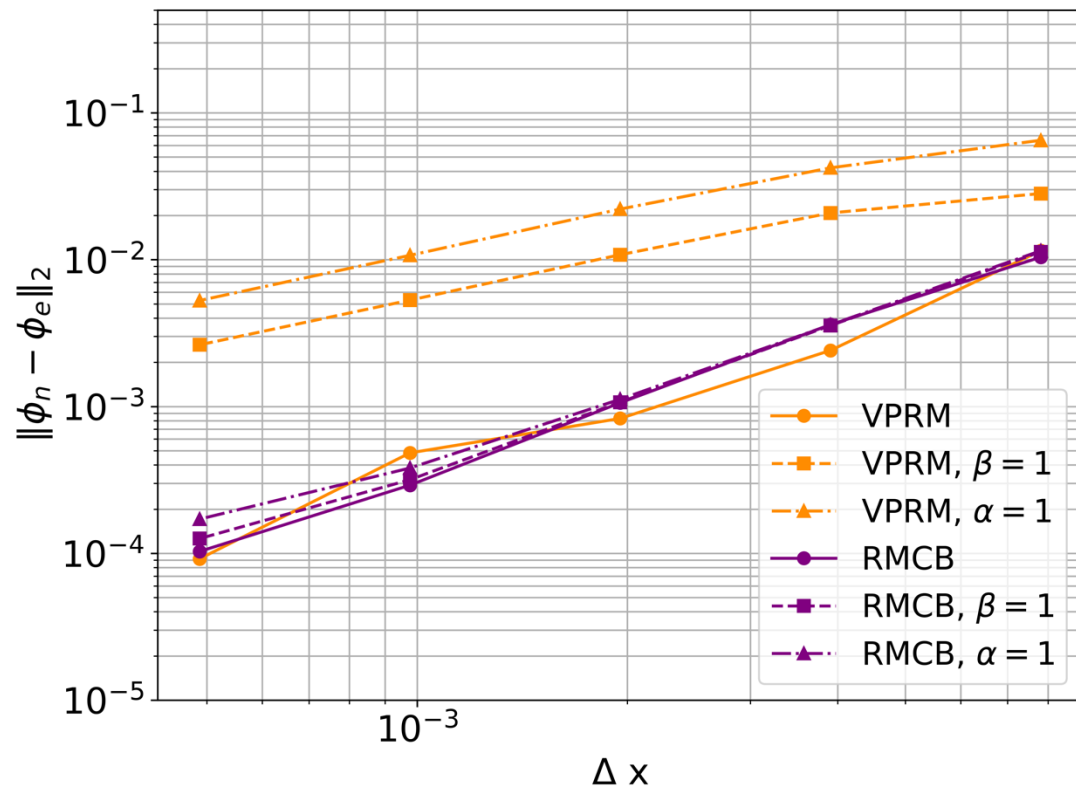
Multiphase Flows



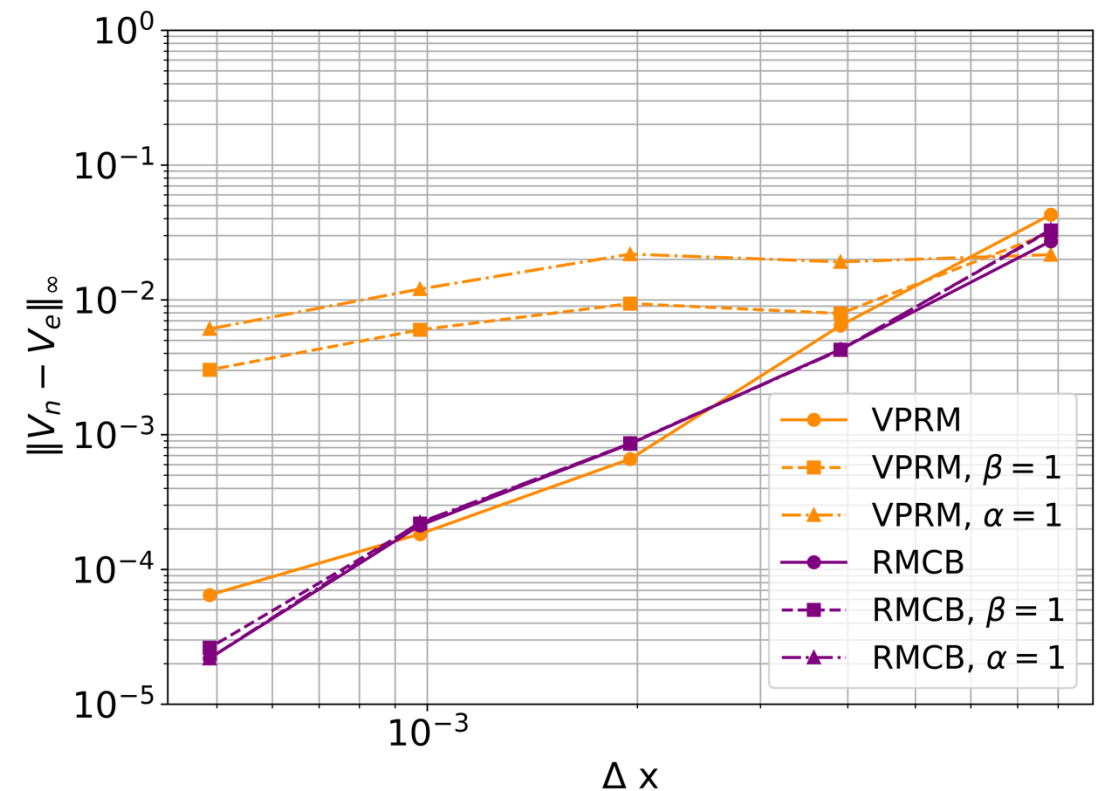
Characteristic Bending

Deforming Flow Results

Interface Error



Volume Error



Characteristic Bending

Non-linear Advection

Incompressible Euler

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla p$$

$$\mathbf{u} = \begin{cases} \sin(x) \cos(y) \\ -\cos(x) \sin(y) \end{cases}$$

$$\nabla p = \begin{cases} \sin(x) \cos(x) \\ \sin(y) \cos(y) \end{cases}$$

$$\frac{Dx}{Dt} = \mathbf{u} \longrightarrow \text{Same}$$

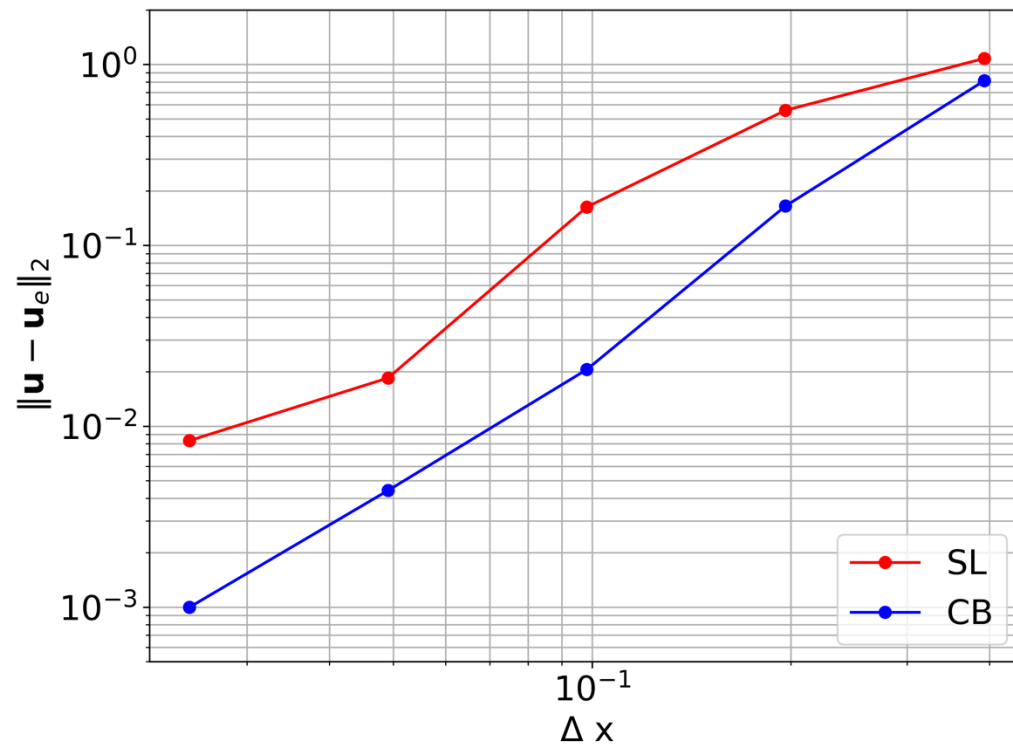
$$\frac{D\mathbf{u}}{Dt} = -\nabla p \quad \searrow$$

$$\mathbf{u}(x, t^{n+1}) = \mathbf{u}(x_d, t^n) - \underbrace{\int_{t^n}^{t^{n+1}} \nabla p(x(\tau), \tau) d\tau}_{\text{New}}$$

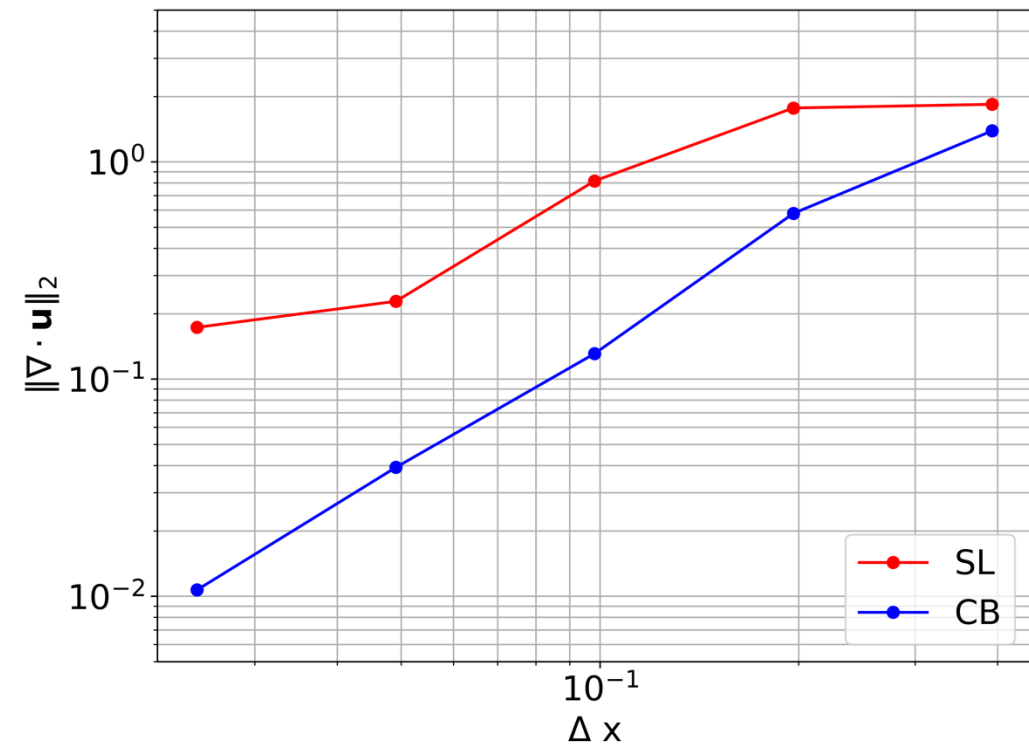
Characteristic Bending

Deviation from the Divergence Free Space

Velocity Error



Divergence Error



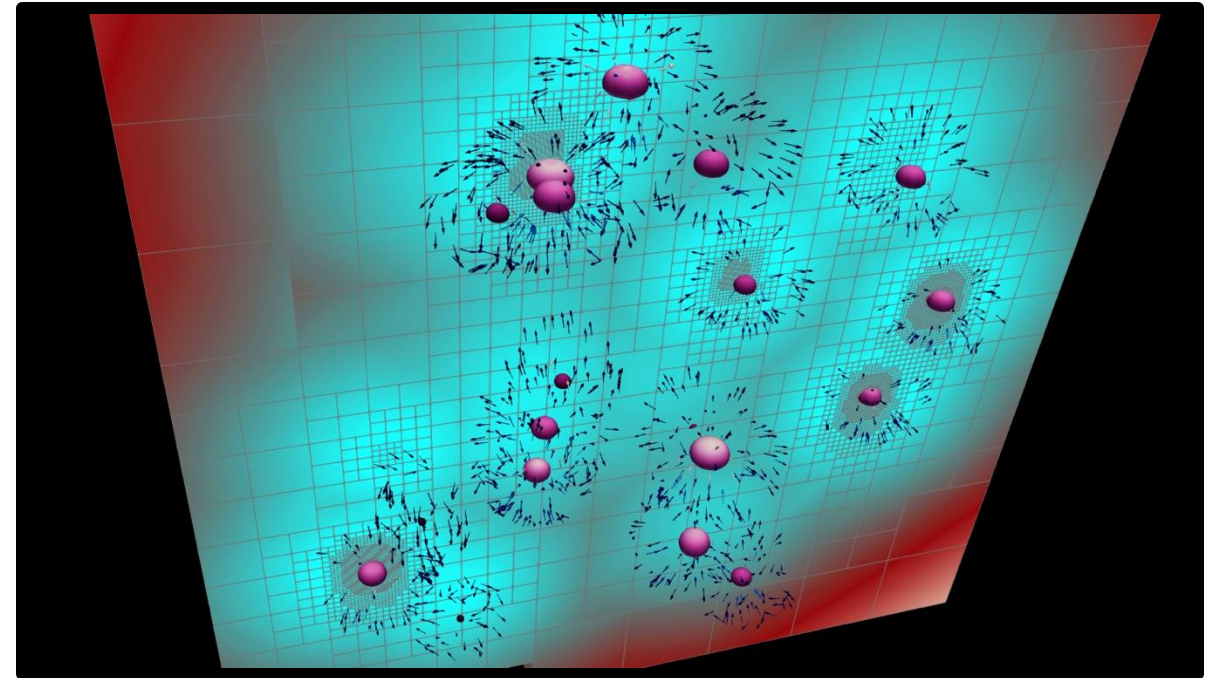
Characteristic Bending

Summary and Next Steps

1. Characteristic Bending (CB) is a robust method for advection under incompressible flows.
2. CB filters compressible modes and preserves divergence-free fields.
3. CB is more expensive than foundational methods and no benefit for exact div-free fields.

Papers

- M. Blomquist, M. Theillard, “Semi-Lagrangian characteristic reconstruction and projection for transport under incompressible fields”, *In preparation*.
- A. Binswanger*, M. Blomquist*, S. R. West, M. Theillard, “Sharp Collocated Projection Method for Immiscible Two-Phase Flows”, arXiv preprint arXiv:2508.11107 (2025)
- M. Blomquist, S. R. West, A. Binswanger, M. Theillard, “Stable nodal projection method on octree grids”, *Journal of Computational Physics* 499, 112695 (2024)



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